A New Vision for Coarray Fortran

John Mellor-Crummey, Laksono Adhianto William Scherer III

Department of Computer Science Rice University

johnmc@cs.rice.edu



Lessons from HPF

- Good parallelizations require proper partitionings
 - —inferior partitionings will fall short at scale
- Excess communication undermines scalability
 - —both frequency and volume must be right!
- Must exploit what smart users know
 - —allow the power user to relax consistency
- Single processor efficiency is critical
 - —node code must be competitive with serial versions
 - —must use caches effectively on microprocessors

Coarray Fortran (CAF)

- Explicitly-parallel extension of Fortran 95 (Numrich & Reid)
- Global address space SPMD parallel programming model
 - —one-sided communication
- Simple, two-level memory model for locality management
 - —local vs. remote memory
- Programmer has control over performance critical decisions
 - —data partitioning
 - —computation partitioning
 - —communication
 - -synchronization
- Suitable for mapping to a range of parallel architectures
 - —shared memory, clusters, hybrid

Classic CAF Programming Model

- SPMD process images
 - —fixed number of images during execution: num_images()
 - —images operate asynchronously: this_image()
- Both private and shared data

```
real x(20, 20)
real y(20, 20) [*]
a private 20x20 array in each image
a shared 20x20 array in each image
```

- Simple one-sided shared-memory communication
 - -x(:,j:j+2) = y(:,p:p+2) [r] copy columns from p:p+2 into local columns
- Synchronization intrinsic functions

```
—sync_all – a barrier and a memory fence—sync_mem – a memory fence
```

- Asymmetric dynamic allocation of shared data
- Weak memory consistency

Why a New Vision?

Fortran 2008 draft specification characteristics

- Coarrays must be allocated over all images
 - —no support for process subsets
- Coarrays must be declared as global variables
 - —no support for dynamic non-global coarrays
- No remote pointers
- No support for collective communication
- Synchronization is not expressive enough
- ... and so on ... (see our critique)
 - —www.j3-fortran.org/doc/meeting/183/08-126.pdf

Outline

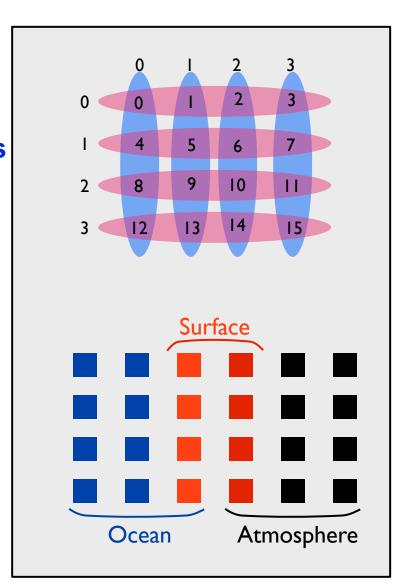
- Coarray Fortran 2.0
 - —Process subsets: teams
 - —Topologies
 - —Copointers
 - —Synchronization
 - —Collective communication
- Summary and ongoing work

Coarray Fortran 2.0 Goals

- Facilitate construction of sophisticated parallel applications and parallel libraries
- Support irregular and adaptive applications
- Hide communication latency
- Colocate computation with remote data
- Scale to petascale architectures
- Exploit multicore processors
- Enable development of portable high-performance programs
- Interoperate with legacy models such as MPI

Process Subsets: Teams

- Teams are first-class entities
 - —ordered sequences of process images
 - —namespace for indexing images by rank r in team t
 - r ∈ {0..team_size(t) 1}
 - —domain for allocating coarrays
 - —substrate for collective communication
- Teams need not be disjoint
 - —an image may be in multiple teams



Creating New Teams

```
team_split (existing_team, color, key, new_team, [new_color=result_color, err_msg=emsg_var])
```

- Images supplying the same color are assigned to the same team
- Each images's rank in the new team is determined by key order
- result_color ≠ color gets handle for another team
 - —used to arrange inter-team communication
 - —alternative to MPI's process groups
- emsg_var receives any error result message
- Predefined team: TEAM_WORLD

Accessing Coarrays on Teams

Accessing a coarray relative to a team

```
-x(i,j)[p@ocean] ! p names a rank in team ocean
```

Accessing a coarray (default)

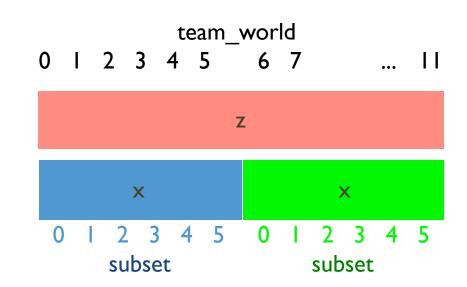
```
-x(i,j)[p] ! p names a rank in team_world (default)
```

Simplifying processor indexing using "with team"

```
with team atmosphere ! make atmosphere the default team
 ! p is wrt team atmosphere, q is wrt team ocean
 x(:,0)[p] = y(:)[q@ocean]
end with team
```

Teams and Coarrays

```
real, allocatable :: x(:,:)[*] ! 2D array
real, allocatable :: z(:,:)[*]
team :: subset
integer :: color, rank
! each image allocates a singleton for z
allocate( z(200,200) [@team world] )
color = floor((2*team_rank(team_world)) /
             team size(team world))
! split into two subsets:
! top and bottom half of team world
team split(team world, color, &
            team rank(team world), subset)
! members of the two subset teams
! independently allocate their own coarray x
allocate(x(100,n)[@ subset])
```



team_rank(team):
 returns the relative rank of the current image
 within a team
team_size(team):
 returns the number of images of a given team

Topology

Motivation

- —a vector of images may not adequately reflect their logical communication structure
- —multiple codimensions only support grid-like logical structures
- —want a single mechanism for expressing more general structures

Topology

- —augments a team with a logical structure for communication
- —more expressive than multiple codimensions

Using Topologies

Creation

```
—Graph: topology_graph(n,e)
—Cartesian: topology_cartesian(/e1,e2,.../)
```

Modification

```
—graph_neighbor_add(g,e,n,nv)
—graph_neighbor_delete(g,e,n,nv)
```

- Binding: topology_bind(team,topology)
- Accessing coarrays using a topology

```
—Cartesian
```

- array(:) [(i1, i2, ..., in)@ocean] ! absolute index wrt team ocean
- array(:) [+(i1, i2, ..., in)@ocean] ! relative index wrt self in team ocean
- array(:) [i1, i2, ..., ik] ! wrt enclosing default team
- —Graph: access kth neighbor of image i in edge class e
 - array(:) [(e,i,k)@g] ! wrt team g
 - array(:) [e,i,k] ! wrt enclosing default team

Cartesian Topology Example

Topology :: Cart

Integer, Allocatable :: X(:)[*], Y(:)[*]

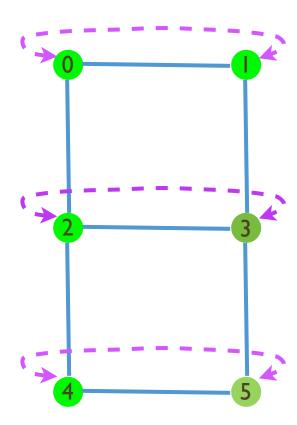
Team :: Ocean, SeaSurface

! create a cartesian topology 2 (cyclic) by 3
Cart = Topology_cartesian(/-2, 3/)

! bind Cart to teams Ocean and SeaSurface Call **Topology_bind**(Ocean, Cart) Call **Topology_bind**(SeaSurface, Cart)

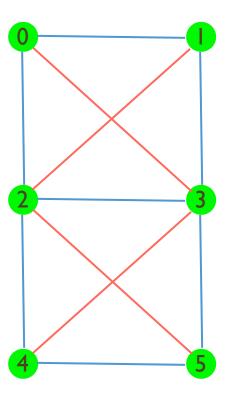
allocate(X(100)[@SeaSurface]) allocate(Y(100)[@Ocean])

! Ocean is the default team in this scope With Team Ocean Y(:) [1, 1] = X(:)[(-1, 2)@SeaSurface] Fnd With Team



Graph Topology Example

```
Topology :: graph
graph = topology_graph(6, 2)
integer :: red, blue, myrank
myrank = team_rank(team_world)
read *, blue_neighbors, red_neighbors
! blue edges
call graph_neighbor_add( graph, blue, myrank, blue_neighbors )
! red edges
call graph_neighbor_add( graph, red, myrank, red_neighbors )
! bind team with the topology
call topology_bind( ocean, graph )
allocate(x(100)@ocean)
y(:) = x(20:80) [ (myrank, blue, 2)@ocean ]
```



Copointers

- Motivation: support linked data structures
- copointer attribute enables association with remote shared data
- imageof(x)returns the image number for x
 - useful to determine whether copointer x is local

```
integer, allocatable :: a(:,:)[*]
integer, copointer :: x(:,:)[*]
allocate(a(1:20, 1:30)[@ team_world]
! associate copointer x with a
! remote section of a coarray
x => a(4:20, 2:25)[p]
! imageof intrinsic returns the target
! image for x
prank = imageof(x)
\mathbf{x}(7,9) = 4! assumes target of x is local
\mathbf{x}(7,9)[] = 4 ! target of x may be remote
```

Synchronization

- Lockset: ordered sets of locks
 - —convenient to avoid deadlock when locking/unlocking multiple locks -- uses a canonical ordering
- Point-to-point synchronization via event variables
 - —like counting semaphores
 - —each variable provides a synchronization context
 - —a program can use as many events as it needs
 - user program events are distinct from library events
 - —event_notify() / event_wait()

Collective Communication

- Collective operations:
 - —usual suspects: broadcast, all/gather, permute, all/reduce, scan, scatter, segmented scan, shift
- Flavors
 - —traditional: two-sided synchronous
 - —new modalities
 - two-sided asynchronous: all start it and later finish it
 - one-sided synchronous: one starts it and blocks until done
 - one-sided asynchronous: one starts it and later finishes it
- A new twist: all/select for min, max, max_copy, min_copy
- User-defined reduction and selection operators
- Split-phase barriers

Summary and Ongoing Work

- CAF 2.0 supports many new features
 - —process subsets (teams), coarrays allocated on teams, dynamic allocation of coarrays, collectives on teams
 - —topologies
 - -copointers
 - —events for safe pair-wise synchronization
 - -locksets
- Provides expressiveness, simplicity and orthogonality
- Source-to-source translator is a work in progress
 - -requires no vendor buy-in
 - —will deliver node performance of mature vendor compilers
- Coming attractions:
 - —cofunctions: remote procedure calls for latency avoidance
 - —coarray binding interface for inter-team communication